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☐ ☐ ☐ LANE DETECTION IS A COMPUTER VISION TASK THAT INVOLVES IDENTIFYING THE BOUNDARIES OF DRIVING LANES IN A VIDEO OR IMAGE OF A ROAD SCENE THE GOAL IS TO ACCURATELY LOCATE AND TRACK THE LANE MARKINGS IN REAL TIME EVEN IN CHALLENGING CONDITIONS SUCH AS POOR LIGHTING GLARE OR COMPLEX ROAD LAYOUTS

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☐ ☐ ☐ 2024☐ 6☐ 14☐ PYTORCHAUTODRIVE SEGMENTATION MODELS ERFNET ENET DEEPLAB FCN AND LANE DETECTION MODELS SCNN RESA LSTR LANEATT B☐ ZIERLANENET BASED ON PYTORCH WITH FAST TRAINING VISUALIZATION BENCHMARKING

ULTRA FAST STRUCTURE AWARE DEEP LANE DETECTION ECCV 2020

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☐ ☐ ☐ ULTRA FAST LANE DETECTION PYTORCH IMPLEMENTATION OF THE PAPER ULTRA FAST STRUCTURE AWARE DEEP LANE DETECTION JULY 18 2022 UPDATES THE NEW VERSION OF OUR METHOD HAS BEEN ACCEPTED BY TPAMI 2022 CODE IS AVAILABLE HERE

LANE2SEQ TOWARDS UNIFIED LANE DETECTION VIA

JAN 17 2024

⬚ ⬚ ⬚ IN THIS PAPER WE PRESENT A NOVEL SEQUENCE GENERATION BASED FRAMEWORK FOR LANE DETECTION CALLED LANE2SEQ IT UNIFIES VARIOUS LANE DETECTION FORMATS BY CASTING LANE DETECTION AS A SEQUENCE GENERATION TASK THIS IS DIFFERENT

REVIEW ON LANE DETECTION AND RELATED METHODS SCIENCEDIRECT

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⬚ ⬚ ⬚ 2023⬚ 1⬚ 1⬚ MODEL BASED AND LEARNING BASED METHODS REPRESENT THE TWO PREDOMINANT TECHNIQUES FOR LANE DETECTION MODEL BASED METHODS AFFORD RAPID COMPUTATION SPEEDS WHILE LEARNING BASED METHODS EXTEND ROBUSTNESS AMIDST COMPLEXITY THIS PAPER DELVES INTO THE TECHNIQUES OF LANE DETECTION AND FORECASTS UPCOMING TRENDS

LANE DETECTION IN AUTONOMOUS VEHICLES A SYSTEMATIC REVIEW

NOV 15 2023

⬚ ⬚ ⬚ 2023⬚ 1⬚ 5⬚ LANE DETECTION DISPLAYS INFORMATION SPECIFIC TO THE GEOMETRICAL FEATURES OF LANE LINE STRUCTURES TO THE VEHICLE S INTELLIGENT SYSTEM TO SHOW THE POSITION OF LANE MARKINGS THIS ARTICLE REVIEWS THE METHODS EMPLOYED FOR LANE DETECTION IN

2105 05403 STRUCTURE GUIDED LANE DETECTION ARXIV ORG

OCT 14 2023

⬚ ⬚ ⬚ 2021⬚ 5⬚ 12⬚ RECENTLY LANE DETECTION HAS MADE GREAT PROGRESS WITH THE RAPID DEVELOPMENT OF DEEP NEURAL NETWORKS AND AUTONOMOUS DRIVING HOWEVER THERE EXIST THREE MAINLY PROBLEMS INCLUDING CHARACTERIZING LANES MODELING THE STRUCTURAL RELATIONSHIP BETWEEN SCENES AND LANES AND SUPPORTING MORE ATTRIBUTES E G INSTANCE AND TYPE OF

2307 06853 LVLANE DEEP LEARNING FOR LANE DETECTION AND

Sep 13 2023

⬚ ⬚ ⬚ 2023⬚ 7⬚ 13⬚   TO ADDRESS THIS WE PRESENT AN END TO END LANE DETECTION AND CLASSIFICATION SYSTEM BASED ON DEEP LEARNING METHODOLOGIES IN OUR STUDY WE INTRODUCE A UNIQUE DATASET METICULOUSLY CURATED TO ENCOMPASS SCENARIOS THAT POSE SIGNIFICANT CHALLENGES FOR STATE OF THE ART SOTA LANE LOCALIZATION MODELS

LANE DETECTION SPRINGERLINK

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⬚ ⬚ ⬚ 2023⬚ 8⬚ 10⬚   GENERALLY A LANE DETECTION SYSTEM SHOULD HAVE THREE BASIC PROPERTIES NAMELY ACCURACY ROBUSTNESS AND EFFICIENCY THE MAIN GOAL OF THE LANE DETECTION ALGORITHM SHOULD BE TO MEET THE REAL TIME SAFETY REQUIREMENTS WITH

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